

Ada Tasking: From the Ravenscar Profile to Dynamic Scheduling

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Tasking

- Ada provides a powerful concurrency model
- No other language has such a wide range of synchronous and asynchronous features
- In this talk we shall look at the extremes

Ravenscar

- Covered in other talks, but
- Simple, predictable, efficient, analyzable
- Static number of 'flat' tasks
- PO for mutual exclusion
- PO with single entry (and no queue) for condition synchronisation
- No rendezvous, select, abort, delay, calendar, dynamic priorities etc
- Simple but safe

Dynamic Scheduling

- Need to support a more flexible computational model
- A task consists of a mandatory **job** and an optional **job**
- Mandatory jobs **must** complete by the deadline
- Optional jobs have **value** and **should** complete by the deadline
- In an overload, value is used to determine which jobs to run and which to abandon
- Better to never start than to abort

Scheduling Results

- EDF (Earliest Deadline First) is optimal if no overload
- EDF is poor if overload
- Value density (V/C) is optimal if deadlines are ignored
- Basic Approach
 - Some form of admission control to prevent overload
 - EDF scheduling of all jobs
 - Mandatory jobs jump to a higher priority (than EDF queue) to ensure they meet their deadlines

Task Attributes

- Period (or arrival interval for sporadic activities)
- Deadline
- Priority promotion time - for mandatory work
- Computation time - mandatory
- Computation time - optional (perhaps minimum ...)
- Priority for mandatory if priority must jump
- Value of optional job

Components

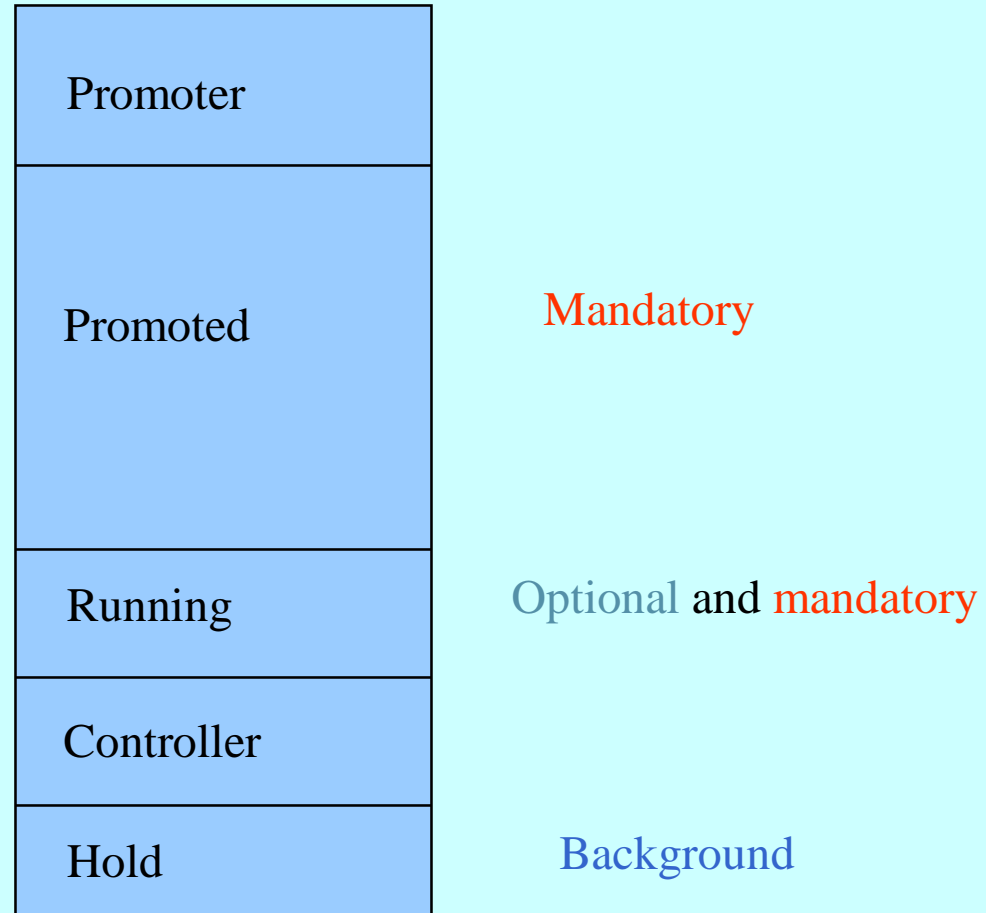
- Client tasks
- Promoter tasks
- Scheduling PO
- EDF queue manager (all jobs)
- Value queue manager (all optional jobs)
- Controller task - runs when new job required

```

package Program_Priorities is
  Hold : constant System.Priority :=
            System.Priority'first + 1;
    -- priority of all task with jobs on EDF queue
  Controller_Pri : constant System.Priority := Hold + 1;
  Running : constant System.Priority := Hold + 2;
    -- priority of running task,
    -- i.e. job just removed from EDF queue
  Pro_Pri : constant System.Priority :=
            System.Priority'last;
    -- promoter task's priority
  subtype Promoted_Priorities is System.Priority range
    Hold + 3 .. System.Priority'last - 1;
    -- priority of tasks executing mandatory
    -- jobs (after promotion)
end Program_Priorities;

```


Priority Map



Parameters of Model

```
package Specific_Parameters is  
  type value is range 0 .. 10; -- say  
  type load is new float range 0.0 .. 10.0; -- say  
    -- load is a measure of current EDF work load  
  threshold : Load := 0.8; -- say  
end Specific_Parameters;
```

Queue Managers

```
package EDF is  
  procedure Add(ID : Task_ID);  
  procedure Remove(ID : Task_ID; Found : out boolean);  
  procedure Extract(ID : out Task_ID; L : out Load);  
end EDF;
```

```
package Value_Manager is  
  procedure Add(ID : Task_ID);  
  procedure Remove(ID : Task_ID);  
  procedure Cut(ID : Task_ID; LD : Load;  
                Admit : out boolean);  
end Value_Manager;
```

Task Attributes

```
package Task_Info is
  type Task_Information is
  record
    Deadline : Time := Time_Last;
    Val : Value := Value'first;
    Comp_Min, Comp_Req : Time_Span := Time_Span_Zero;
    Man_Fin : boolean := false;
  end record;

  Default : Task_Information;
  -- default object is needed in
  -- definition of task attributed

package Scheduling_Parameter is new
  Ada.Task_Attributes(Task_Information, Default);
end Task_Info;
```

Promoter Task

```
task type Promoter is
  entry set_times(Start_T : Time; HP : Priority;
                  Period,R_Deadline,R_Pro : Time_Span);
  pragma priority(Pro_Pri);
end Promoter;

type Pro is access Promoter;

task body Promoter is
  My_Period : Time_Span;
  Pro_Time : Time_Span;
  Rel_Deadline : Time_Span;
  TP : Task_Information;
  High : Priority;
  Client : Task_ID;
  Epoch : Time;
begin
```

```
accept Set_Times(Start_T : Time; HP : Priority;  
                Period,R_Deadline,R_Pro : Time_Span) do  
  My_Period := Period;  
  Epoch := Start_T;  
  High := HP;  
  Pro_Time := R_Pro;  
  Rel_Deadline := R_Deadline;  
  Client := Set_Times'Caller;  
end Set_Times;  
loop  
  delay until Epoch + Pro_Time;  
  TP := Scheduling_Parameter.Value(Client);  
  if not TP.Man_Fin then  
    set_priority(High,Client);  
  end if;  
  delay until Epoch + Rel_Deadline;  
  set_priority(High,Client);  
  Epoch := Epoch + My_period;  
end loop;  
end Promoter;
```

```
task type Example_Client(My_Priority:
                        Promoted_Priorities) is
    pragma Priority(My_Priority);
end Example_Client;
```

```
task body Example_Client is
    Start : Time;
    Period : Time_Span := ...
    Rel_Deadline : Time_Span := ...
    Abs_Deadline : Time;
    Rel_Promotion_Time : Time_Span := ...
    Mandatory_Finished : boolean;
    Self : Task_ID;
    Quality : Value;
    Timing_Error : exception;
    Minimum_Comp_Man : Time_Span := ...
    Required_Comp_Man : Time_Span := ...
    Minimum_Comp_Opp : Time_Span := ...
    Required_Comp_Opp : Time_Span := ...
    P : Pro := new Promoter;
begin
```

```
begin
  Start := clock;
  Self := Current_Task;
  P.set_times(Start, My_Priority, Period, Rel_Deadline,
              Rel_Promotion_Time);
loop
  Mandatory_Finished := false;
  Abs_Deadline := Start + Rel_Deadline;
  select
    delay until Abs_Deadline;
    if not Mandatory_Finished then
      raise Timing_Error;
    end if;
  then abort
    -- stuff
  end select;
  Start := Start + Period;
  delay until Start;
end loop;
exception when ...
end Example_Client;
```


then abort

```
Quality := Value'last;
scheduling_parameter.set_value((Abs_Deadline,
    Quality, Minimum_Comp_Man,
    Required_Comp_Man, Mandatory_Finished));
Sch.Register_Mandatory(Self);
-- Mandatory Job
Mandatory_Finished := true;
Sch.Remove_Mandatory(Self);
Quality := ... Not Value'last
scheduling_parameter.set_value((Abs_Deadline,
    Quality, Minimum_Comp_Opp, Required_Comp_Opp,
    Mandatory_Finished));
Sch.Register_Optional(Self);
-- Optional Job
end select;
```

Scheduler PO

```
protected Sch is  
  entry Release_New;  
  procedure Register_Mandatory(C1 : Task_ID);  
  procedure Remove_Mandatory(C1 : Task_ID);  
  procedure Register_Optional(C1 : Task_ID);  
  pragma Priority(Pro_Pri);  
private  
  Num_on_EDF : natural := 0;  
end Sch;
```

Controller task

```
task Controller is  
    pragma Priority(Controller_Pri);  
end Controller;
```

```
task body Controller is  
begin  
    loop  
        Sch.Release_New;  
    end loop;  
end Controller;
```

```
protected body Sch is
```

```
    procedure Register_Mandatory(C1 : Task_ID) is
```

```
    begin
```

```
        EDF.Add(C1);
```

```
        Num_on_EDF := Num_on_EDF + 1;
```

```
        Set_Priority(Hold,C1);
```

```
    end;
```

```
    procedure Remove_Mandatory(C1 : Task_ID) is
```

```
        Found : boolean;
```

```
    begin
```


```
        EDF.Remove(C1,Found);
```

```
        if Found then
```

```
            Num_on_EDF := Num_on_EDF - 1;
```

```
        end if;
```

```
    end;
```



```
procedure Register_Optional(C1 : Task_ID) is  
begin  
    EDF.Add(C1);  
    Num_on_EDF := Num_on_EDF + 1;  
    Value_Manager.Add(C1);  
    Set_Priority(Hold,C1);  
end;
```

```
entry Release_New when Num_on_EDF > 0 is
  ID : Task_ID;
  LD : Load;
  TP : Task_Information;
  Run_it : boolean;
begin
  EDF.extract(ID,LD);
  Num_on_EDF := Num_on_EDF - 1;
  TP := Scheduling_Parameter.Value(ID);
  if TP.Val = Value'last then -- mandatory part
    Set_Priority(Running, ID);
    return;
  end if;
  if clock + TP.Comp_Min > TP.Deadline then
    Value_Manager.Remove(ID); -- not worth starting
    requeue Release_New;
  end if;
  ...
```

```
if LD <= Threshold then  -- no overload
    Value_Manager.Remove(ID);
    Set_Priority(Running, ID);
    return;
end if;
Value_Manager.Cut(ID, LD, Run_it); -- overload
if Run_it then
    Set_Priority(Running, ID);
else
    requeue Release_New; -- find another task
end if;
end Release_New;
```

Features Used

- Tasks and Protected Objects
- Rendezvous
- Dynamic Priorities
- Task Attributes
- Select-then-Abort
- Requeue

Feature Missing from Ada

- Computation time management

```
select  
    delay 7.0; -- execution time  
then abort  
    code  
end select;
```

Conclusions

- Ada has nearly all the features needed to program flexible schedulers
- The tasking model has high expressive power
- It is a vehicle by which scheduling results can be moved into industrial practice
- Lack of control over execution time is a drawback - to be rectified in the next version of Ada?